

Ascent: Flyweight In Situ Visualization and Analysis for HPC Simulations

Part of the SC21 Tutorial:

In Situ Analysis and Visualization with SENSEI and Ascent

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Acknowledgements





EXASCALE COMPUTING PROJECT

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Important links and contact info:

Ascent Resources:

- Github: https://github.com/alpine-dav/ascent
- Docs: http://ascent-dav.org/
- Tutorial Landing Page: https://www.ascent-dav.org/tutorial/

Presenter Contact Info:



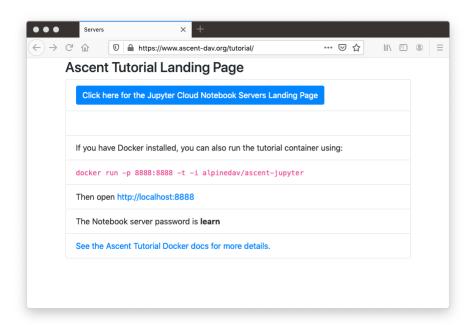
Cyrus Harrison: cyrush@llnl.gov



You can run our tutorial examples using cloud hosted Jupyter Lab servers

Start here:

https://www.ascent-dav.org/tutorial/





Ascent is an easy-to-use flyweight in situ visualization and analysis library for HPC simulations

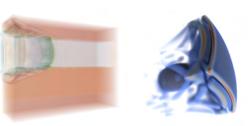
Easy to use in-memory visualization and analysis

- Use cases: Making Pictures, Transforming Data, and Capturing Data
- Young effort, yet already supports most common visualization operations
- Provides a simple infrastructure to integrate custom analysis
- Provides C++, C, Python, and Fortran APIs

Uses a flyweight design targeted at next-generation HPC platforms

- Efficient distributed-memory (MPI) and many-core (CUDA or OpenMP) execution
 - Demonstrated scaling: In situ filtering and ray tracing across 16,384 GPUs on LLNL's Sierra Cluster
- Has lower memory requirements than current tools
- Requires less dependencies than current tools (ex: no OpenGL)
 - Builds with Spack https://spack.io/





Visualizations created using Ascent





Extracts supported by Ascent

http://ascent-dav.org
https://github.com/Alpine-DAV/ascent

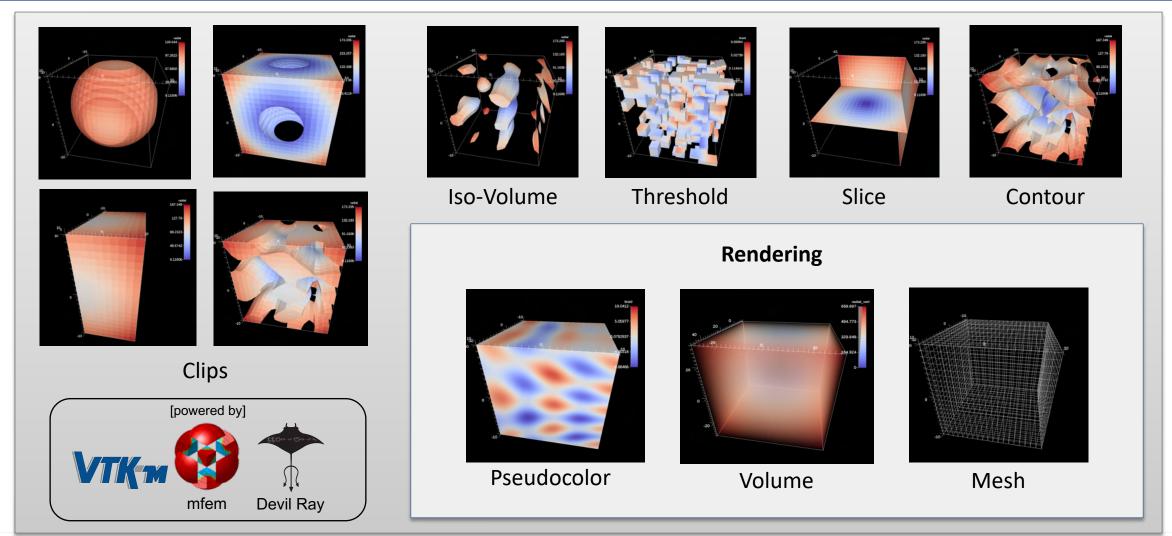
Website and GitHub Repo







Ascent is ready for common visualization use cases

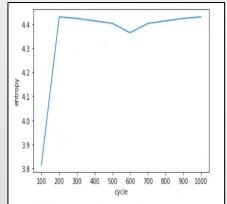


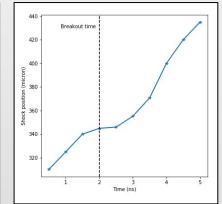


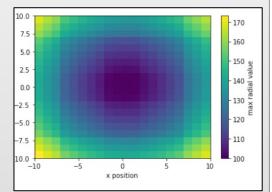


Ascent is ready for common analysis use cases

```
expression: |
  du = gradient(field('velocity','u'))
  dv = gradient(field('velocity','v'))
  dw = gradient(field('velocity','w'))
  w_x = dw.y - dv.z
  w_y = dw.z - dv.x
  w_z = dw.x - dv.y
  vector(w_x,w_y,w_z)
  name: vorticity
```





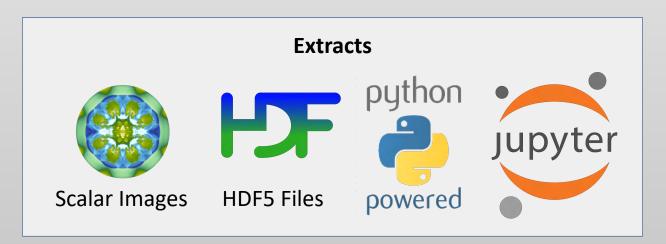


Derived Fields

Triggers

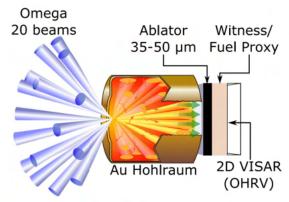
Time Histories

Lineouts and Spatial Binning

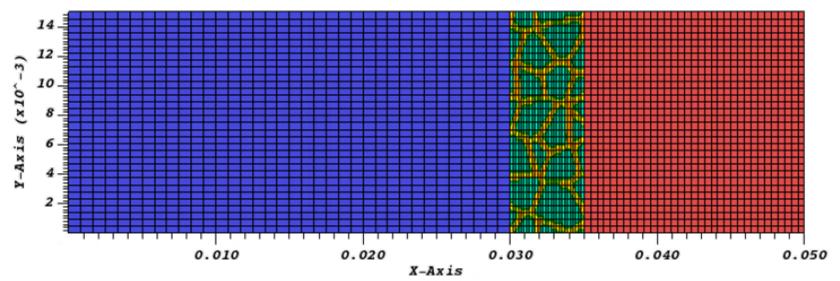




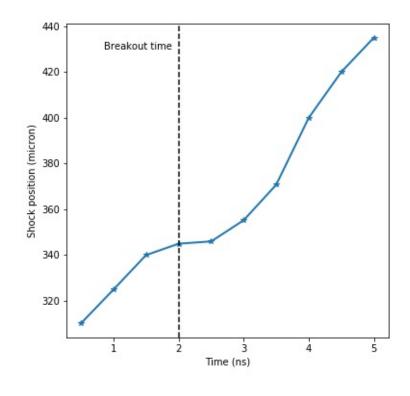
Science Enabling Results: Shock Front Tracking (VISAR)



Velocity interferometer system for any reflector (VISAR)



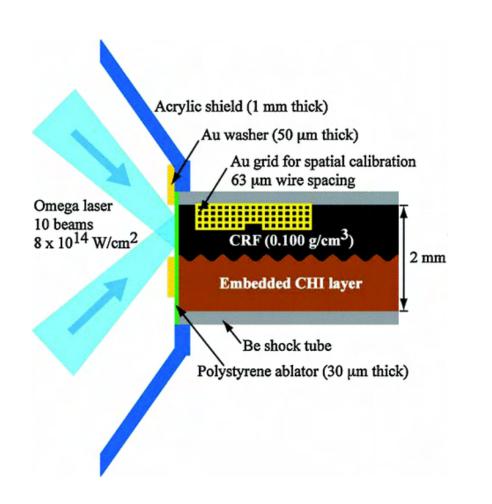
Shock position tracked in Ascent







Science Enabling Results: Simulation Validation



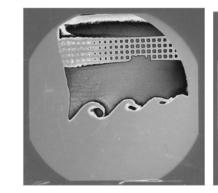
Radiographs

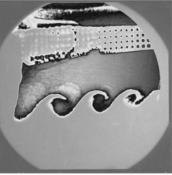
Simulated





Experimental

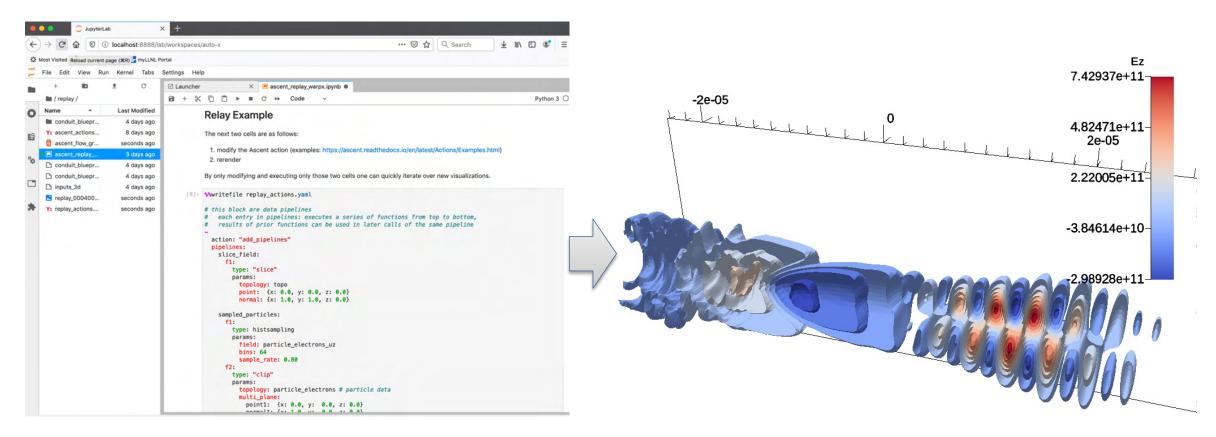








Science Enabling Results: WarpX Workflow Tools (Jupyter Labs)



Jupyter Labs Interface

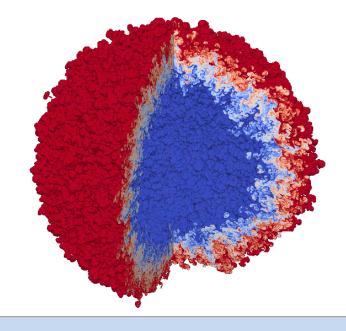
Resulting Image





Science Enabling Results: Rendering At Scale (2018)

- The 97.8 billion element simulation ran across
 16,384 GPUs on 4,096 Nodes
- The simulation application used CUDA via RAJA to run on the GPUs
- Time-varying evolution of the mixing was visualized in-situ using **Ascent**, also leveraging 16,384 GPUs
- Ascent leveraged VTK-m to run visualization algorithms on the GPUs



Visualization of an idealized Inertial Confinement Fusion (ICF) simulation of Rayleigh-Taylor instability with two fluids mixing in a spherical geometry.



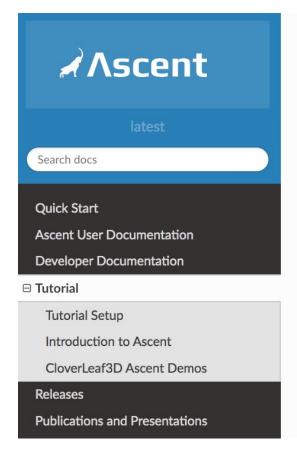
Today we will teach you about Ascent's API and capabilities

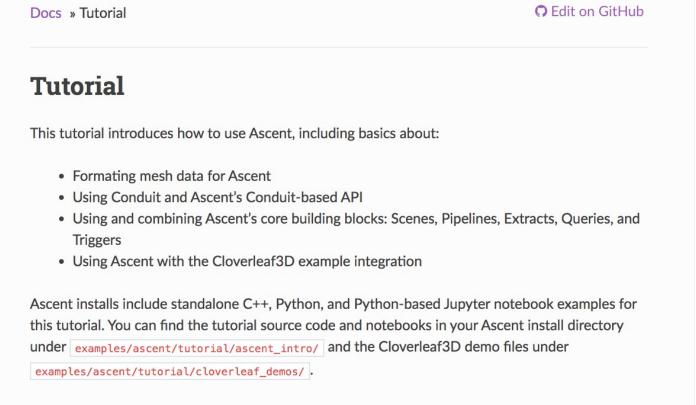
You will learn:

- How to use Conduit, the foundation of Ascent's API
- How to get your simulation data into Ascent
- How to tell Ascent what pictures to render and what analysis to execute



Ascent tutorial examples are outlined in our documentation and included ready to run in Ascent installs





http://ascent-dav.org

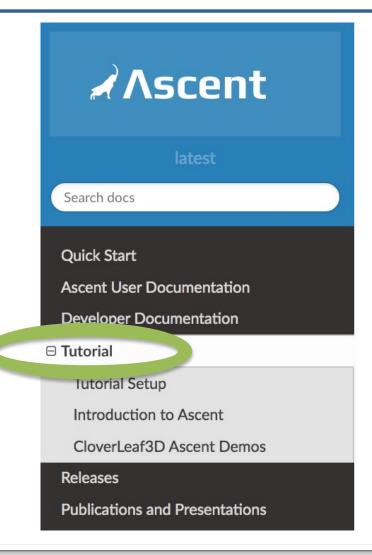




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http://ascent-dav.org

Click on "Tutorial"





Ascent's interface provides five top-level functions

- open() / close()
 - Initialize and finalize an Ascent instance
- publish()
 - Pass your simulation data to Ascent
- execute()
 - Tell Ascent what to do
- info()
 - Ask for details about Ascent's last operation

```
//
// Run Ascent
//

Ascent ascent;
ascent.open();

ascent.publish(data);
ascent.execute(actions);
ascent.info(details);

ascent.close();
```

The *publish(), execute()* and *info()* methods take a Conduit tree as an argument.

What is a Conduit tree?



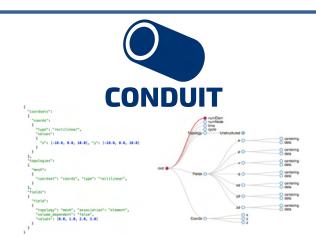
Conduit provides intuitive APIs for in-memory data description and exchange

Provides an intuitive API for in-memory data description

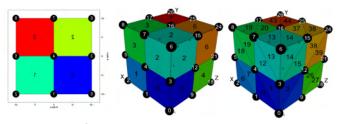
- Enables human-friendly hierarchical data organization
- Can describe in-memory arrays without copying
- Provides C++, C, Python, and Fortran APIs

Provides common conventions for exchanging complex data

- Shared conventions for passing complex data (e.g. Simulation Meshes) enable modular interfaces across software libraries and simulation applications
- Provides easy to use I/O interfaces for moving and storing data
 - Enables use cases like binary checkpoint restart
 - Supports moving complex data with MPI (serialization)



Hierarchical in-memory data description



Conventions for sharing in-memory mesh data

http://software.llnl.gov/conduit
http://github.com/llnl/conduit

Website and GitHub Repo





Ascent uses Conduit to provide a flexible and extendable API

- Conduit underpins Ascent's support for C++, C, Python, and Fortran interfaces
- Conduit also enables using YAML to specify Ascent actions
- Conduit's zero-copy features help couple existing simulation data structures
- Conduit Blueprint provides a standard for how to present simulation meshes

Learning Ascent equates to learning how to construct and pass Conduit trees that encode your data and your expectations.



https://ascent.readthedocs.io/en/latest/Tutorial_Intro_First_Light.html

```
#include <iostream>
#include "ascent.hpp"
#include "conduit blueprint.hpp"
using namespace ascent;
using namespace conduit;
int main(int argc, char **argv)
   // echo info about how ascent was configured
   std::cout << ascent::about() << std::endl;
   // create conduit node with an example mesh using
   // conduit blueprint's braid function
   // ref: https://llnl-conduit.readthedocs.io/en/latest/blueprint_mesh.html#braid
   // things to explore:
   // changing the mesh resolution
   Node mesh;
   conduit::blueprint::mesh::examples::braid("hexs",
                                             50,
                                                                              This code generates an example mesh
                                             50.
                                             50,
                                             mesh);
```





https://ascent.readthedocs.io/en/latest/Tutorial_Intro_First_Light.html

```
// create an Ascent instance
Ascent a;

Create an Ascent instance and set it up

// open ascent
a.open();

// publish mesh data to ascent
a.publish(mesh);

Now Ascent has access to our mesh data
```



https://ascent.readthedocs.io/en/latest/Tutorial_Intro_First_Light.html

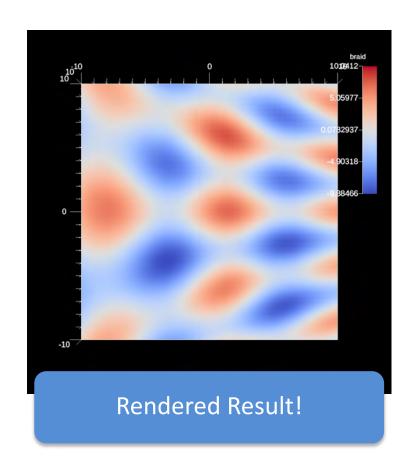
```
// Ascent's interface accepts "actions"
                                                                    Create a tree that describes the actions we
// that to tell Ascent what to execute
                                                                                     want Ascent to do
Node actions;
Node &add_act = actions.append();
add_act["action"] = "add_scenes";
// Create an action that tells Ascent to:
// add a scene (s1) with one plot (p1)
                                                                                 action: "add_scenes"
// that will render a pseudocolor of
                                                                                 scenes:
// the mesh field 'braid'
                                                                                    s1:
Node & scenes = add act["scenes"];
                                                                                      plots:
// things to explore:
                                                                                         p1:
// changing plot type (mesh)
                                                                                           type: "pseudocolor"
// changing field name (for this dataset: radial)
                                                                                           field: "braid"
scenes["s1/plots/p1/type"] = "pseudocolor";
scenes["s1/plots/p1/field"] = "braid";
                                                                                       image_name: "out_first_light_render_3d"
// set the output file name (ascent will add ".png")
scenes["s1/image name"] = "out first light render 3d";
// view our full actions tree
                                                                       Equivalent YAML Description
std::cout << actions.to_yaml() << std::endl;
```



https://ascent.readthedocs.io/en/latest/Tutorial_Intro_First_Light.html

```
// execute the actions
a.execute(actions);
```

Tell Ascent to execute these actions





Ascent's interface provides five composable building blocks

Scenes

(Render Pictures)

Pipelines

(Transform Data)

Extracts

(Capture Data)

Queries

(Ask Questions)

Triggers

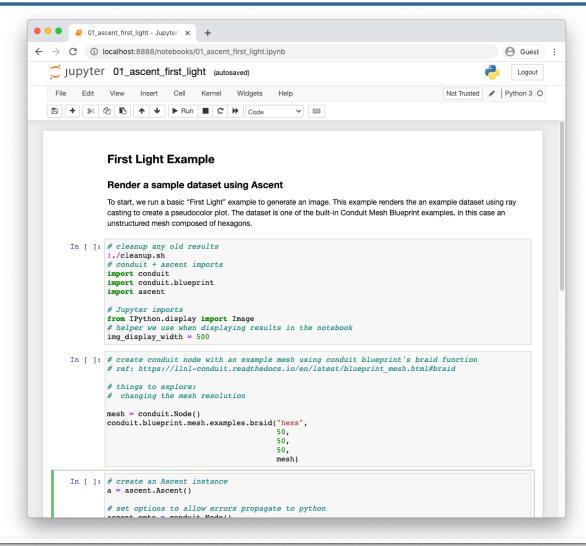
(Adapt Actions)

The tutorial provides examples for all of these.





For the reminder of the tutorial, we will run the Ascent Tutorial examples using Jupyter Notebooks

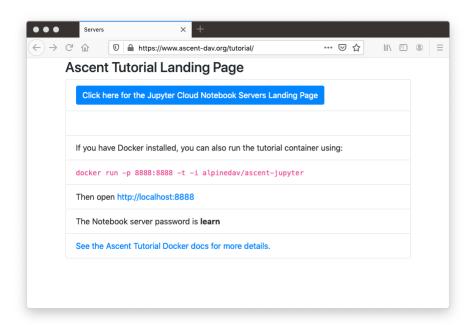




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Thanks!

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